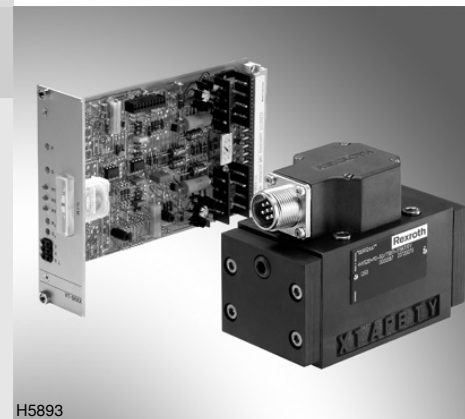


4/3 directional servo-valve with mechanical position feedback

RE 29583-XN-114-B2/10.10
Replaces: 04.07

Type 4WS2EM 10...XN...-114

Size 10
Component series 5X
Maximum operating pressure 315 bar
Maximum flow 180 l/min



**ATEX units
For explosive areas**

Part II Data sheet



Information on explosion protection:

Range of application in accordance with the Explosion Protection Directive 94/9/EC

II3G: Type of protection Ex nA II T5X according to EN 60079-0:2006 / EN 60079-15:2005

II3D: Type of protection Ex tD A22 IP 65 TX according to EN 61241-0:2006 / EN 61241-1:2004

What you need to know about these operating instructions

These operating instructions apply to the explosion-proof version of Rexroth valves and consist of the following three parts:

Part I General information 07010-X-B1

Part II Data sheet 29583-XN-114-B2

Part III Product-specific instructions 29583-XN-114-B3

Operating instructions 29583-XN-114-B0

You can find further information on the correct handling of Rexroth hydraulic products in our publication "General product information on hydraulic products" 07008.

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Features

- Directional servo-valve for proper use in explosive areas of zone 2 and 22
- Valve to control position, force, pressure or velocity
- 2-stage servo valve with mechanical feedback
- 1st stage as nozzle flapper plate amplifier
- For subplate mounting, porting pattern according to ISO 4401-05-05-0-05 with ports X and Y subplates available in FE/ZN version (see page 11)
- Dry control motor, no contamination of the solenoid gap by the hydraulic fluid
- Can also be used as 3-way version
- Wear-free spool feedback element
- Control: External control electronics in Eurocard format or in modular design (separate order), see page 6
- Valve is adjusted and tested
- Internal/external pilot oil supply and return can be ordered individually
- Spool with flow force compensation
- Control sleeve centrally fixed; thus low susceptibility to temperature and pressure
- Pressure chambers at the control sleeve with gap seals, therefore no wear of the seal ring
- Filter for 1st stage freely accessible from the outside

Ordering code and scope of delivery

4WS2E	M	10-5X/	B	11	XN			K31		V-114
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Electrically actuated
2-stage servo valve in
4/3 directional design for
external control electronics

Mechanical feedback = M

Size = 10

Component series 50 to 59
(50 to 59: unchanged installation and
connection dimensions) = 5X

Rated flow ¹⁾

5 l/min	= 5
10 l/min	= 10
20 l/min	= 20
30 l/min	= 30
45 l/min	= 45
60 l/min	= 60
75 l/min	= 75
90 l/min	= 90

Valve for **external** control electronics
coil no. 11 (30 mA/85 Ω per coil) ²⁾

= 11

Included in the delivery:

- Valve mounting screws
- Valve operating instructions with declaration of conformity in part III

1) Rated flow

The rated flow refers to a 100% command value signal at 70 bar valve pressure differential (35 bar per control edge). The valve pressure differential must be regarded as reference. Other values result in the flow being changed. A possible rated flow tolerance of ±10% must be taken into account (see flow signal function page 7).

2) External control electronics

The actuating signal must be created from a flow-controlled output stage with a superimposed dither signal. Control electronics (servo amplifier) see page 6.

3) Pilot oil

Care should be taken that the pilot pressure is as constant as possible. An external pilot control via port X is thus often advantageous.

The valve can be operated with a higher pressure at X than at P in order to influence the dynamics in a positive form.

114 = Special number ⁶⁾

Seal material

V = FKM seals
suitable for mineral oil
(HL, HLP) according to
DIN 51524

Spool overlap ⁵⁾

E = 0 ... 0.5 % negative
D = 0 ... 0.5 % positive
C = 3 ... 5 % positive

Electrical connection

K31 = with connector
Mating connector – separate order,
see page 6

Inlet pressure range to the 1st stage ⁴⁾

210 = 10 to 210 bar
315 = 10 to 315 bar

Pilot oil supply and return ³⁾

- = Supply external, return external
E = Supply internal, return external
T = Supply external, return internal
ET = Supply internal, return internal
(ET = Standard version)

XN = Explosion protection "type nA"
For details see information on the explosion protection,
page 6

Important:

The ports X and Y are also pressurized in case of "internal" pilot oil supply and return.

4) Inlet pressure range

Care should be taken that the system pressure is as constant as possible. Pilot pressure range: 10 ... 210 bar or 10 ... 315 bar

With regard to the dynamics, the frequency response dependency must be observed within the admissible pressure range.

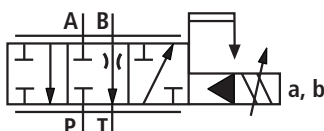
5) Spool overlap

The spool overlap is specified in % of the control spool stroke.

6) Special number "114"

Without actuation (de-energized condition), channel B → T is open for 10 % of the nominal quantity. In the control area, port A is always blocked.

Symbol



Function, section

4WS2EM 10-5X/...XN...-114

Valves of this type are electrically operated, 2-stage directional servo-valves with porting pattern according to ISO 4401-05-05-0-05. They are mainly used to control position, force, pressure or velocity.

These valves are made of an electro-mechanical converter (torque motor) (1), a hydraulic amplifier (principle: nozzle flapper plate) (2) and a control spool (3) in a sleeve (2nd stage) which is connected with the torque motor via a mechanical feedback.

An electrical input signal at the coils (4) of the torque motor generates a force by means of a permanent magnet which acts on the armature (5), and in connection with a torque tube (6) results in a torque. This causes the flapper plate (7) which is connected to the torque tube (6) via a pin to move from the central position between the two control nozzles (8), and a pressure differential is created across the front faces of the control spool (3). The pressure differential results in the spool changing its position, which results in the pressure port being connected to one actuator port and, at the same time, the other actuator port being connected to the return flow port.

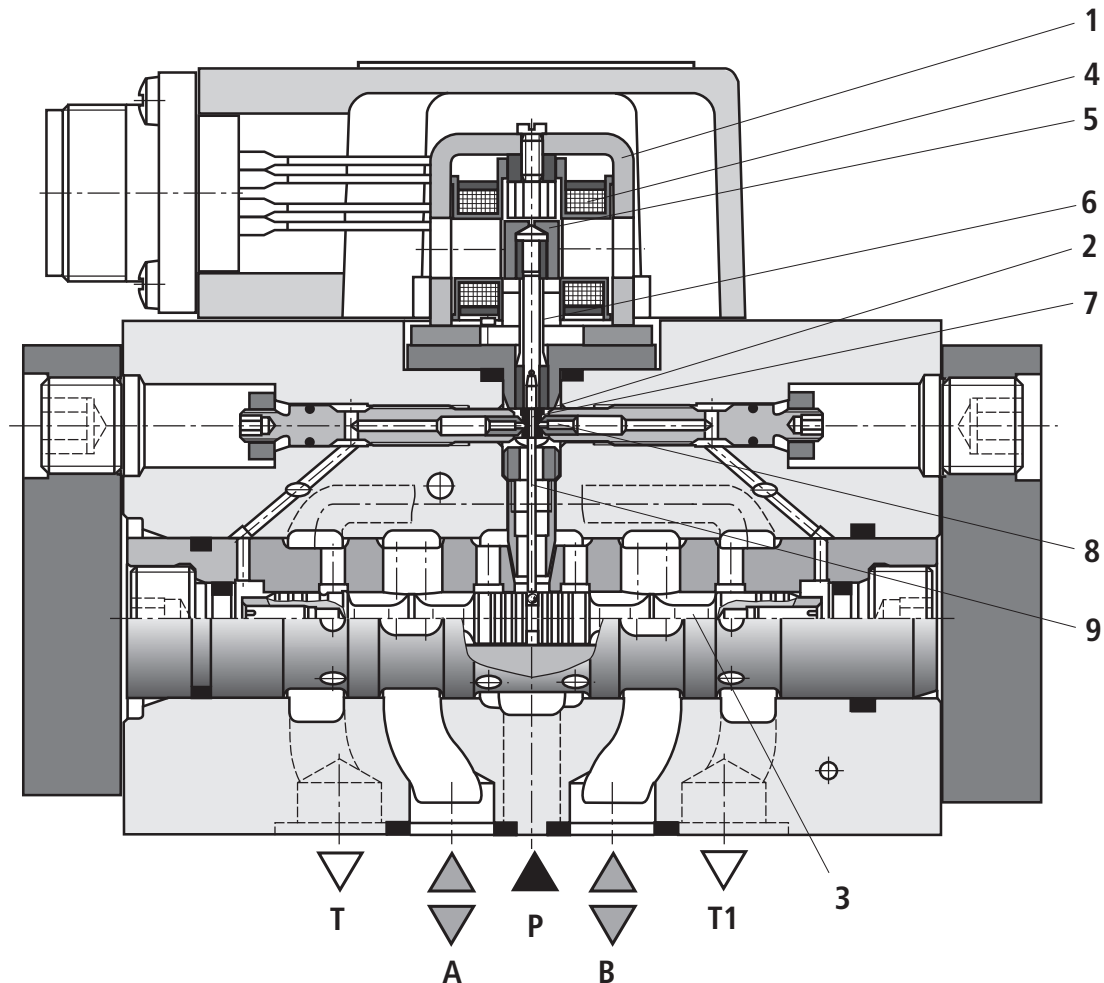
The control spool is connected to the flapper plate or the torque motor by means of a bending spring (mechanical feedback) (9). The position of the spool is changed until the feedback torque across the bending spring and the electro-magnetic torque of the torque motor are balanced and the pressure differential at the nozzle flapper plate system becomes zero.

The stroke of the control spool and consequently the flow of the servo valve are controlled in proportion to the electrical input signal. It must be noted that the flow depends on the valve pressure drop.

External control electronics (separate order)

External control electronics (servo amplifier) serve the actuation of the valve, amplifying an analog input signal (command value) so that with the output signal, the servo valve is actuated in a flow-controlled form.

Type 4WS2EM 10...XN...-114



Technical data

general

Porting pattern		ISO 4401-05-05-0-05
Installation position		Any (Ensure that upon system start-up, the pilot control is supplied with enough pressure (≥ 10 bar)!))
Surface protection	Valve body, cover, filter screw	Nitro-carburated
	Cap	Anodized
Storage temperature range	°C	-20 ... +80
Ambient temperature range	°C	-30 ... +80
Weight	kg	3.56

hydraulic (measured with HLP 32, $\vartheta_{oil} = 40^\circ\text{C} \pm 5^\circ\text{C}$)

Operating pressure	Pilot control stage, pilot oil supply	bar	10 ... 210 or 10 ... 315							
	Main valve, ports P, A, B	bar	to 315							
Return flow pressure	Port T									
	Pilot oil return internal	bar	Pressure peaks <100 permitted							
	Pilot oil return external	bar	to 315							
	Port Y	bar	Pressure peaks <100 permitted, static < 10							
Hydraulic fluid			Mineral oil (HL, HLP) according to DIN 51524 ignition temperature > 150 °C							
Hydraulic fluid temperature range	°C		-15 ... +80; preferably +40 ... +50							
Viscosity range	mm ² /s		15 ... 380; preferably 30 ... 45							
Maximum admissible degree of contamination of the hydraulic fluid, cleanliness class according to ISO 4406 (c)			Class 18/16/13 ¹⁾							
Zero flow $q_{V,L}^{2)}$ with spool overlap E measured without dither signal	l/min		$\frac{p_P^{4)}}{70 \text{ bar}} \cdot 0,7 \frac{\text{l}}{\text{min}}$	$\frac{p_P^{4)}}{70 \text{ bar}} \cdot 0,9 \frac{\text{l}}{\text{min}}$	$\frac{p_P^{4)}}{70 \text{ bar}} \cdot 1,2 \frac{\text{l}}{\text{min}}$	$\frac{p_P^{4)}}{70 \text{ bar}} \cdot 1,5 \frac{\text{l}}{\text{min}}$	$\frac{p_P^{4)}}{70 \text{ bar}} \cdot 1,7 \frac{\text{l}}{\text{min}}$			
Rated flows $q_{V, rated}^{3)}$, tolerance $\pm 10\%$ with valve pressure differential $\Delta p = 70$ bar (35 bar/edge)	l/min		5	10	20	30	45	60	75	90
Max. control spool stroke possible with mechanical end position (in case of error) related to nominal stroke	%		120 ... 170				120 ... 150			
Feedback system			Mechanical							
Hysteresis (dither-optimized)	%		$\leq 1,5$							
Range of inversion (dither-optimized)	%		$\leq 0,3$							
Response sensitivity (dither-optimized)	%		$\leq 0,2$							
Pressure gain with 1 % spool stroke change (from the hydraulic zero point)	% of $p_P^{4)}$		≥ 30				≥ 60		≥ 80	
Zero adjustment flow over the entire operating pressure range	%		≤ 3 , long-term ≤ 5							
Zero shift upon change of:										
Hydraulic fluid temperature	% / 20 K		≤ 1							
Ambient temperature	% / 20 K		≤ 1							
Operating pressure 80 ... 120 % of $p_P^{4)}$	% / 100 bar		≤ 2							
Return flow pressure 0 ... 10 % of $p_P^{4)}$	% / bar		≤ 1							

¹⁾ The cleanliness classes specified for the components must be adhered to in hydraulic systems. Effective filtration prevents faults and at the same time increases the service life of the components. For the selection of filters, see www.boschrexroth.com/filter

²⁾ $q_{V,L}$ = Zero flow in l/min

³⁾ $q_{V, rated}$ = Rated flow in l/min

⁴⁾ p_P = Operating pressure in bar

Technical data

electric

Protection class according to EN 60529:1991+A1:2000	IP 65 with mating connector correctly mounted and locked		
Type of signal	Analog		
Rated current per coil	mA	30	
Resistance per coil	Ω	85	
Inductivity with 60 Hz and 100% rated current	Connection in series	H	1.0
	Connection in parallel	H	0.25

In case of actuating using non-Rexroth amplifiers, we recommend a superimposed dither signal

Information on explosion protection

Range of application as per directive 94/9/EC	II 3 G; II 3 D		
Type of protection according to EN 60079-0:2006 / EN 60079-15:2005	Ex nA II T5X		
Type of protection according to EN 61241-0:2006 / EN 61241-1:2004	Ex tD A22 IP 65 TX		
Maximum surface temperature	$^{\circ}\text{C}$	100	
Ambient temperature range	$^{\circ}\text{C}$	-30 ... +80	
Hydraulic fluid temperature range	$^{\circ}\text{C}$	-15 ... +80	
Max. admissible operating voltage of the servo amplifier	V	32 (DC)	

External control electronics

Servo amplifier (separate order)	Eurocard format	analog	Type VT-SR2-1X/.60 according to data sheet 29980
	Modular design	analog	Type VT 11021 according to data sheet 29743

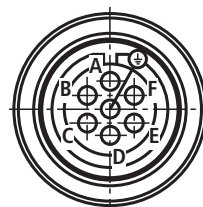
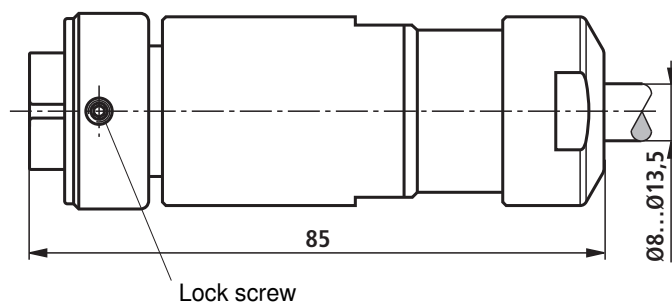
The coils of the valve may only be connected in parallel to these amplifiers!

⚠ WARNING – Risk of explosion

– The external servo amplifier must be operated outside the explosive area!

Mating connector

The servo valve may only be supplied through this mating connector.



Electrical connection acc. to EN 175201-804

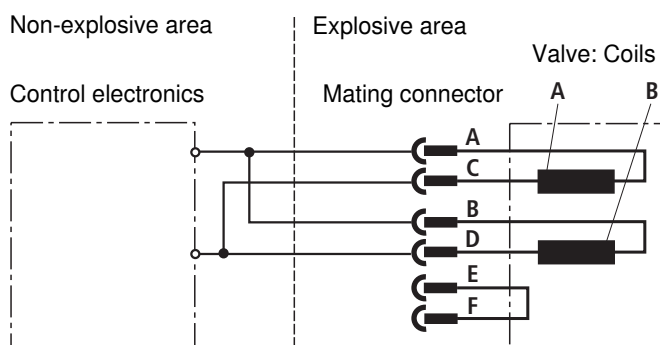
Metal version

Separate order under the material no. **R901044595**

Connection:

Contact sockets with soldered joints for litz wires 0.5 ... 1.5 mm²

Electrical connection (example of parallel connection)



The coils are connected in parallel in the mating connector or at the amplifier (see figure).

In case of serial connection, contacts B and C must be connected.

The E-F bridge can be used for the electrical determination of the correct connection of the plug-in connector and/or for the identification of cable break.

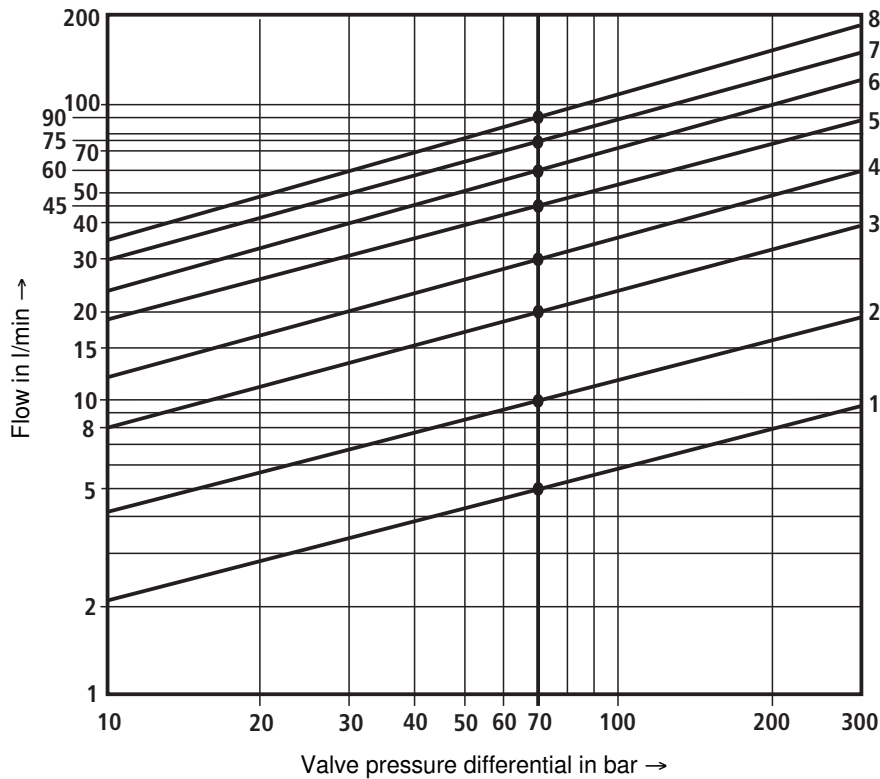
The electrical actuation from A (+) to D (-) causes flow direction from B → T. The reverse electrical actuation causes a flow direction of P → B.

Characteristic curves (measured with HLP 32, $\vartheta_{oil} = 40^\circ\text{C} \pm 5^\circ\text{C}$)

Flow/load function (tolerance $\pm 10\%$) with 100 % command value signal

Important:

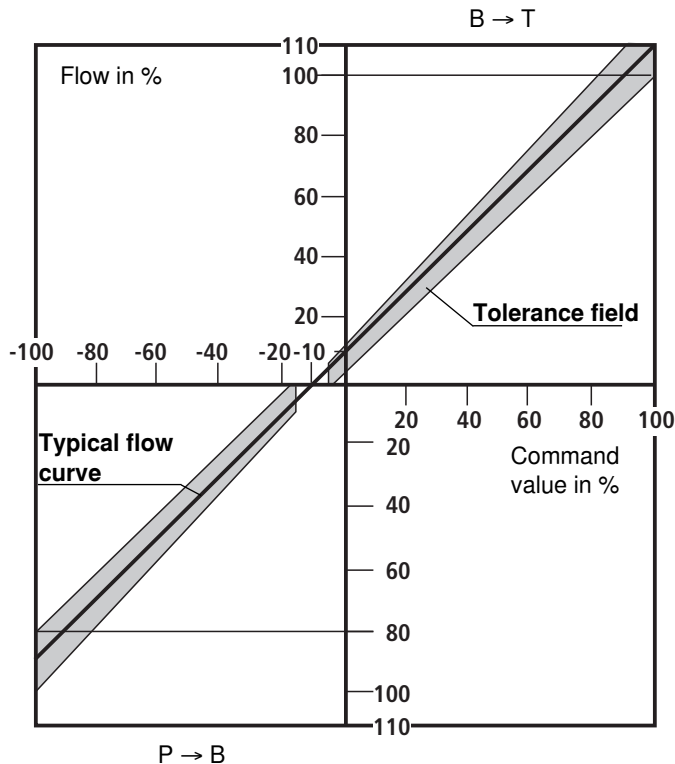
Observe flow values in the max. command value range (see tolerance field of the flow/signal function)



Ordering code	Rated flow	Curve
5	5 l/min	1
10	10 l/min	2
20	20 l/min	3
30	30 l/min	4
45	45 l/min	5
60	60 l/min	6
75	75 l/min	7
90	90 l/min	8

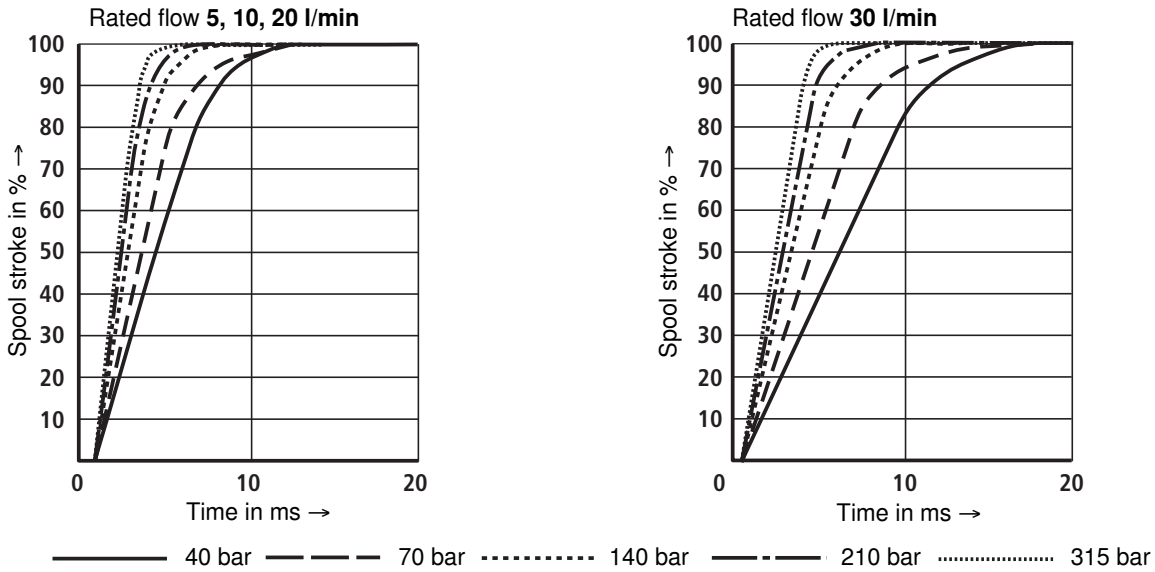
Δp = Valve pressure differential (inlet pressure p_p minus load pressure p_L minus return flow pressure p_T)

Tolerance field of the flow/signal function at constant valve pressure differential Δp

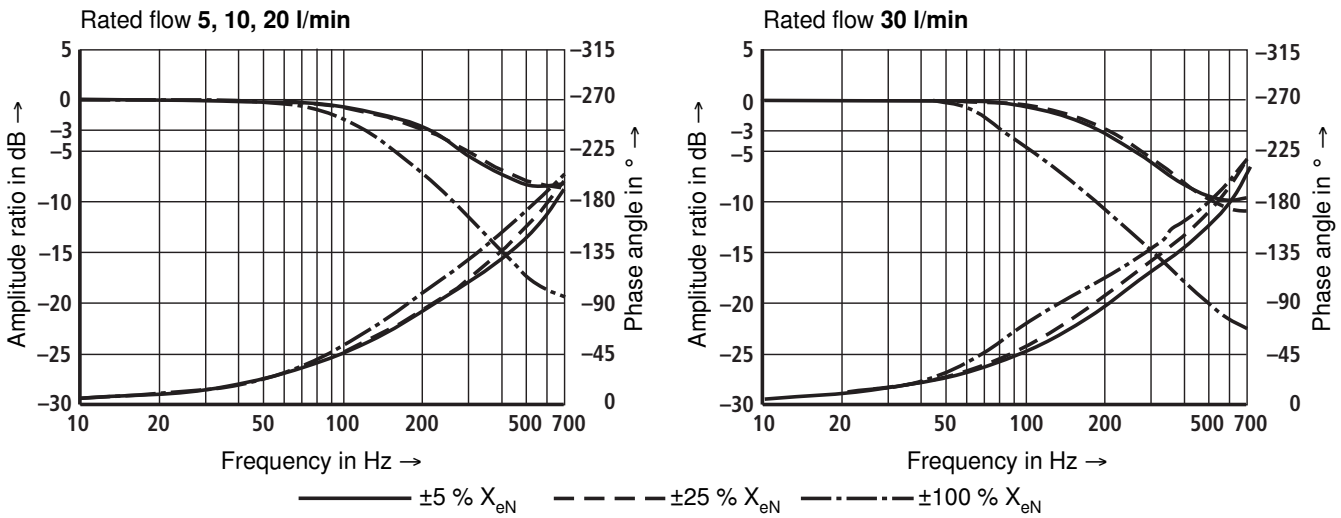


Characteristic curves (measured with HLP 32, $\vartheta_{oil} = 40^\circ\text{C} \pm 5^\circ\text{C}$)

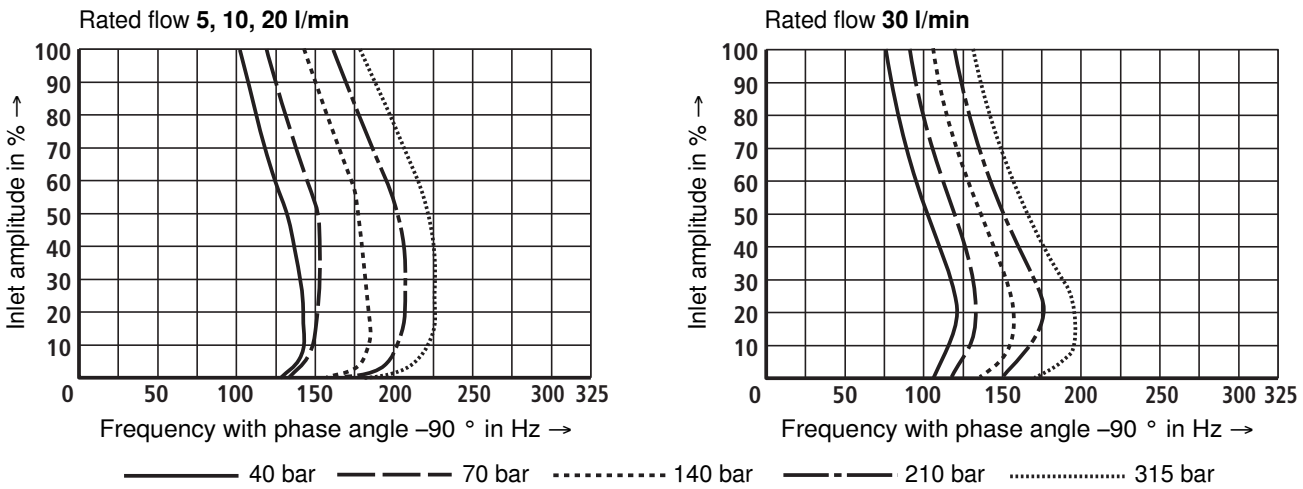
Transition function with pressure rating 315 bar, step response without flow



Frequency response with pressure rating 315 bar, stroke frequency without flow

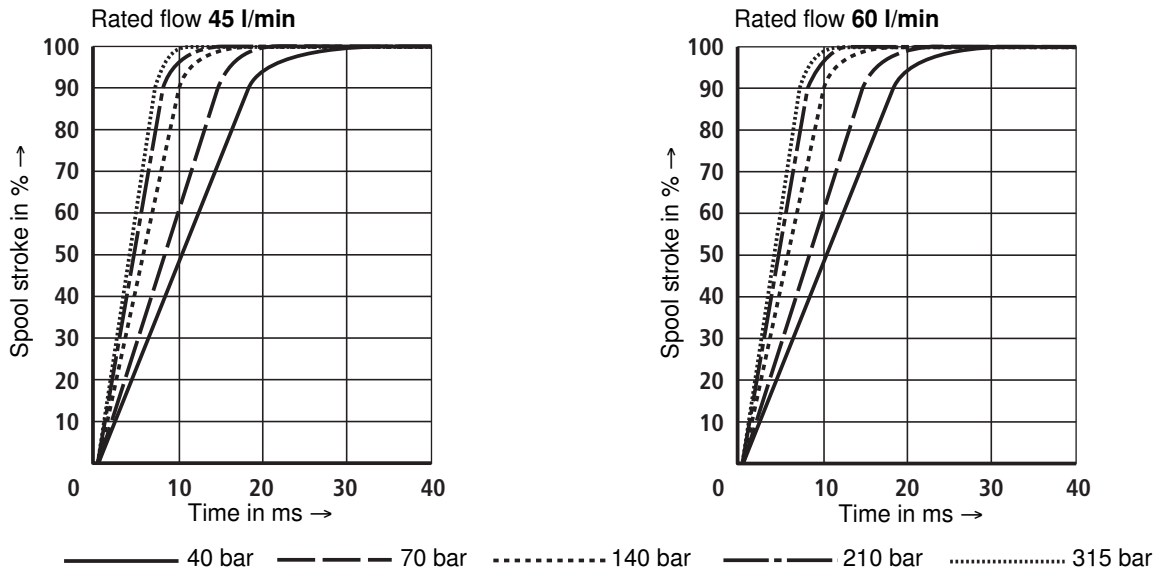


Dependency of the frequency f at -90° on the operating pressure p and the inlet amplitude

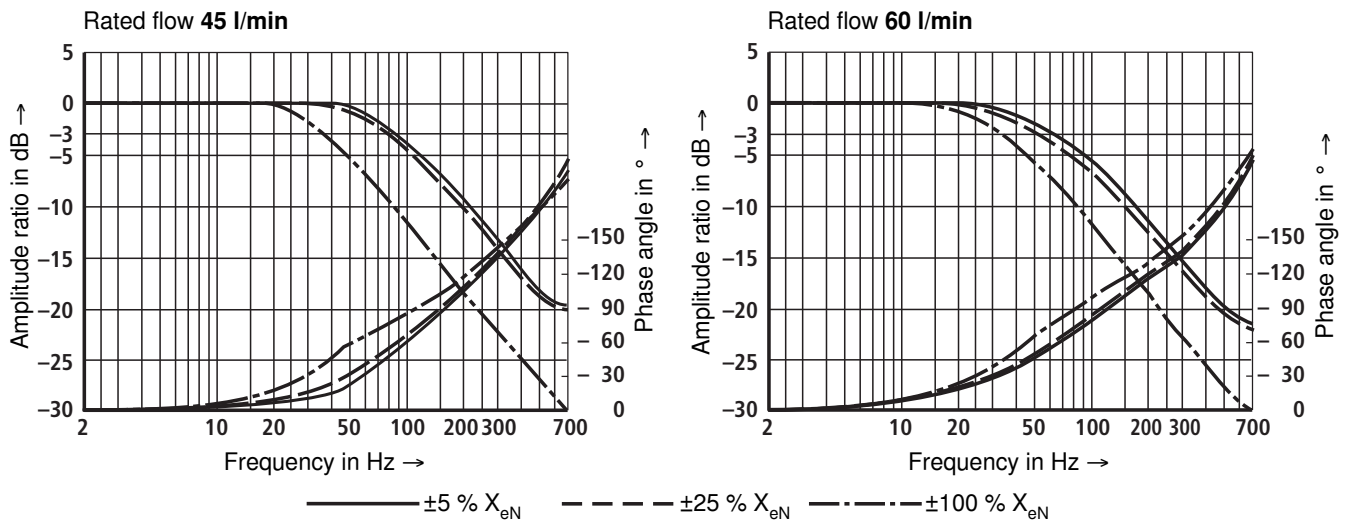


Characteristic curves (measured with HLP 32, $\vartheta_{oil} = 40^\circ C \pm 5^\circ C$)

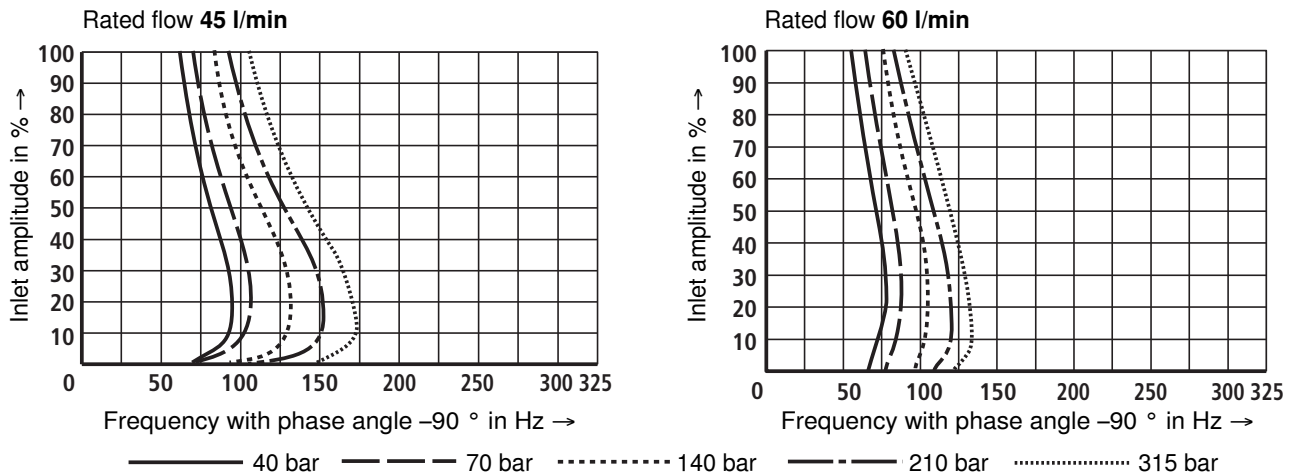
Transition function with pressure rating 315 bar, step response without flow



Frequency response with pressure rating 315 bar, stroke frequency without flow

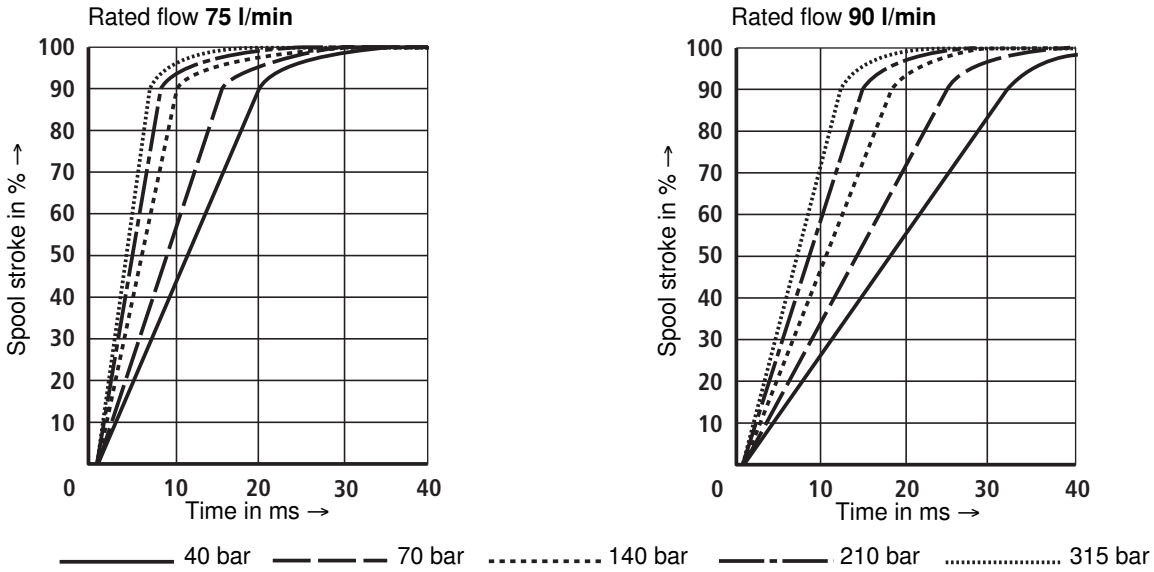


Dependency of the frequency f at -90° on the operating pressure p and the inlet amplitude

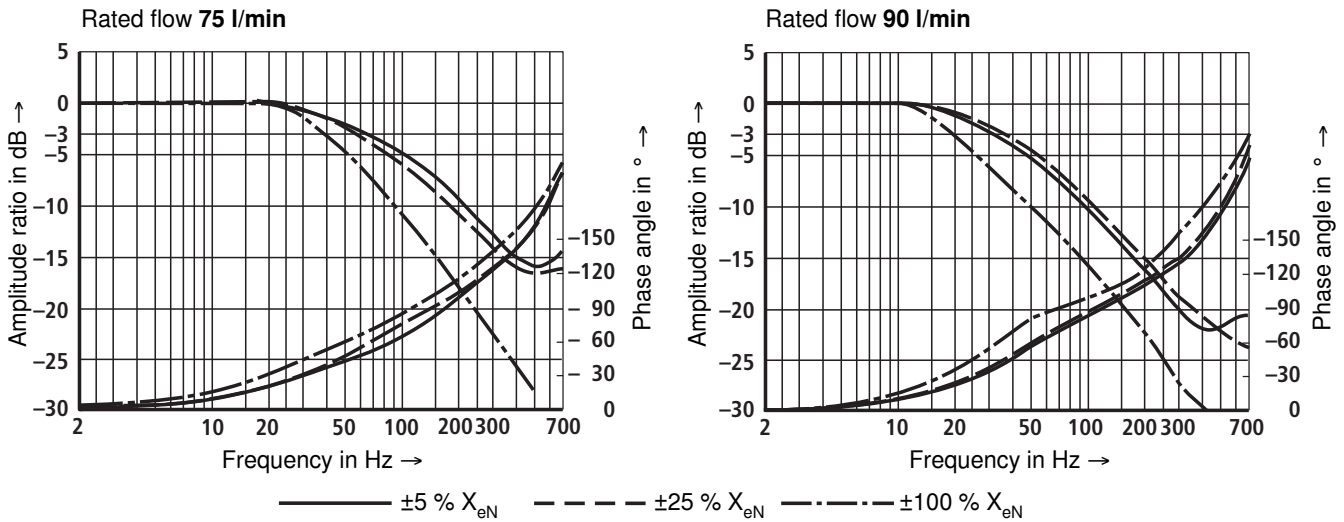


Characteristic curves (measured with HLP 32, $\vartheta_{oil} = 40^\circ\text{C} \pm 5^\circ\text{C}$)

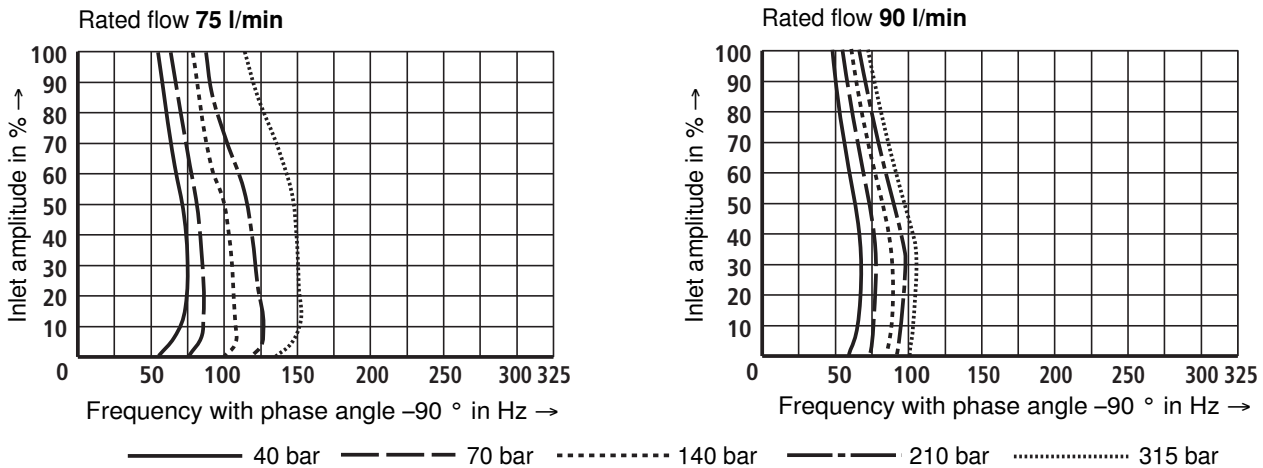
Transition function with pressure rating 315 bar, step response without flow



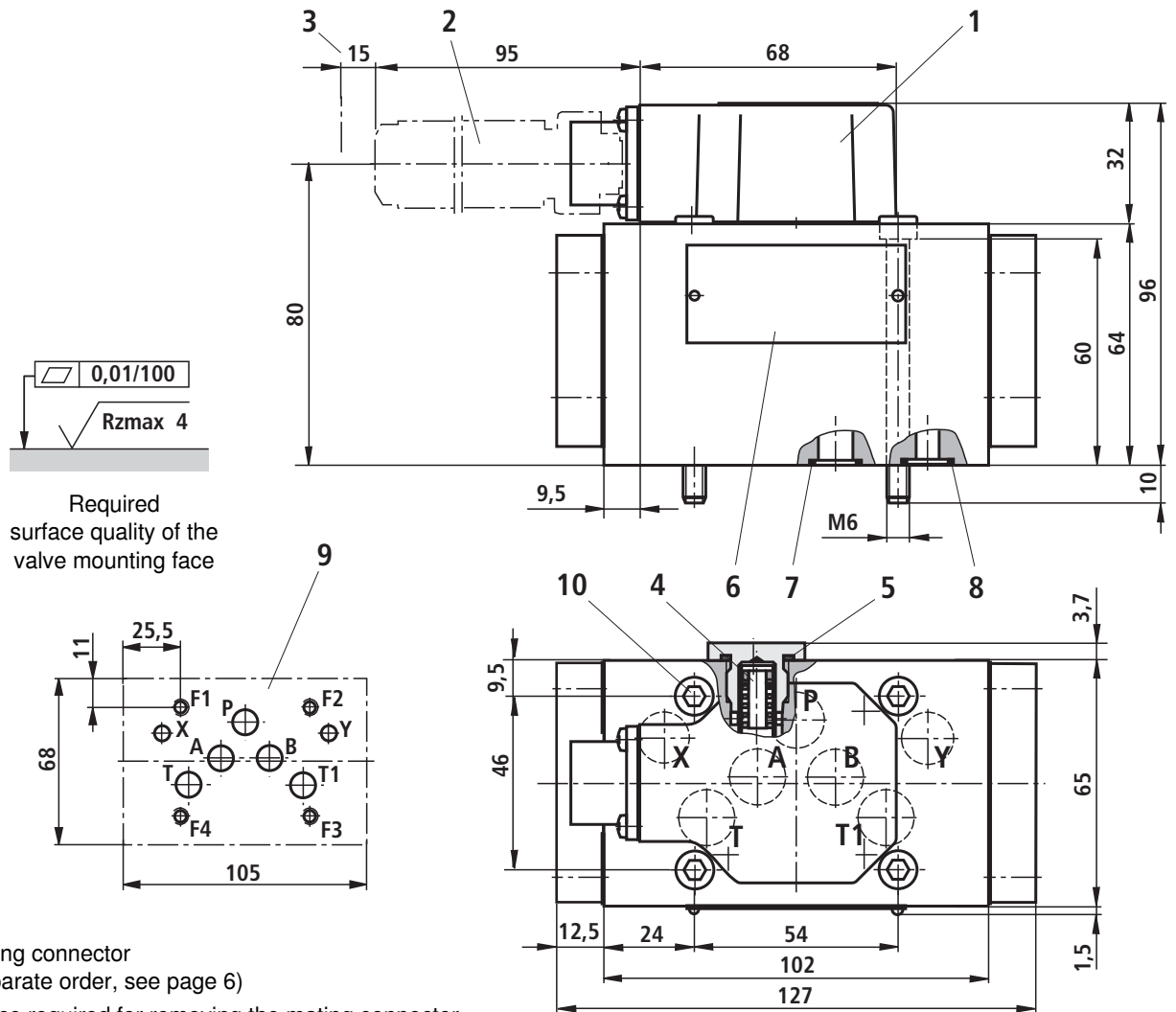
Frequency response with pressure rating 315 bar, stroke frequency without flow



Dependency of the frequency f at -90° on the operating pressure p and the inlet amplitude



Unit dimensions (dimensions in mm)



Required surface quality of the valve mounting face

- 1 Cap
- 2 Mating connector
(separate order, see page 6)
- 3 Space required for removing the mating connector, additionally observe the bending radius of the connection line
- 4 Exchangeable filter element
material no.: **R900306843**
- 5 Profile seal for filter screw M16 x 1.5
material no.: **R900012503** (FKM seal)
- 6 Name plate
- 7 Identical seal rings for ports P, A, B, T and T1
- 8 Identical seal rings for ports X and Y
Ports X and Y are also pressurized in case of "internal" pilot oil supply and return.
- 9 Processed valve mounting face
Porting pattern according to ISO 4401-05-05-0-05
Port T1 is optional and is recommended for reducing the pressure drop from B → T with rated flows > 45 l/min.
- 10 Valve mounting screws
For reasons of stability, exclusively the following valve mounting screws may be used:
4 hexagon socket head cap screws
ISO 4762-M6x70-10.9-fIZn-240h-L
(Friction coefficient 0.09 – 0.14 according to VDA 235-101) (included in the delivery)

Subplates

G 66/01 FE/ZN (G3/8)
G 67/01 FE/ZN (G1/2)

with ports X and Y:

G 535/01 FE/ZN (G3/4)
G 535/02 FE/ZN (M27 x 2)
G 536/01 FE/ZN (G1)
G 536/02 FE/ZN (M33 x 2)

with dimensions as in the data sheet 45054 (must be ordered separately)

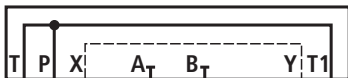
Important:

Subplates are no components in the sense of directive 94/9/EC and can be used after the manufacturer of the overall system has assessed the risk of ignition.

The G...FE/ZN versions are free from aluminum and/or magnesium and galvanized.

Flushing plate with porting pattern according to ISO 4401-05-05-0-05 (dimensions in mm)

Symbol



Ordering code and more information

- Material number: **R900912450**
- Weight: 2 kg
- Identical seal rings for ports P, A, B, T and T1
- Identical seal rings for ports X and Y
- Mounting screws
For reasons of stability, exclusively the following mounting screws may be used:
4 hexagon socket head cap screws
ISO 4762-M6x50-10.9-fIZn-240h-L
(friction coefficient 0.09 - 0.14 according to VDA 235-101) (included in the delivery)

Important

Before the assembly, observe the information in the Product-specific instructions 29583-XN-114-B3, section 3.2.

